UCMERCED MESA Lab

Fractional Order Thinking

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Sept. 7, 2012. Friday 12:00-13:20
COB 267

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Thinking on "… thinking"

- Computational Thinking (CPS)
- Control Thinking
- System Thinking
- Multidisciplinary Thinking
- Cyber-Physical Thinking (CPS)
- Lumped Parameter Thinking
- …
- **Fractional Order Thinking**

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My submission - "Computational" can be put in front of almost every thing

- Computational intelligence
- Computational material
- Computational neuron science
- Computational psychology
- Computational fluid dynamic
- Computational biology
- Computational chemistry
- Computational ecology
- Computational social science
- Computational virology
- ….

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My submission - "Control" can be put after almost every thing

- Speed Control
- Diet Control
- Weight Control
- Emotion Control
- Arm Control
- Microclimate Control
- Machine Control
- Human Gait Control
- Blood-pressure Control
- Aging Control
- Evacuation Control/Traffic Control/Conggestion Control
- ….

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Fractional Order Thinking

- a.k.a "fractional order dynamic system thinking"
- Fractional order dynamics in either spatial evolution axis or temporal evolution axis.
- **Due to the complexity of the system, fractional order thinking may become essential to obtain additional insights and conclude more rationally.**
- Bruce J. West. ***Where Medicine Went Wrong: Rediscovering the Path to Complexity***. World Scientific Publishing Company. 2006. **ISBN-13:** 978-9812568830

Outline

- Fractional Calculus and Fractional Order Thinking
- From Control, Signal Processing to Energy Informatics and Beyond
- Concluding Remarks

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- From Control, Signal Processing to Energy Informatics and Beyond
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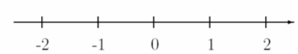
. . . from integer to non-integer . . .



$$x^n = \underbrace{x \cdot x \cdot \ldots \cdot x}_{n}$$

$$x^n = e^{n \ln x}$$

$$n! = 1 \cdot 2 \cdot 3 \cdot \ldots \cdot (n-1) \cdot n,$$

$$\Gamma(x) = \int_0^\infty e^{-t} t^{x-1} dt, \qquad x > 0,$$

$$\Gamma(n+1) = 1 \cdot 2 \cdot 3 \cdot \ldots \cdot n = n!$$

Slide credit: Igor Podlubny

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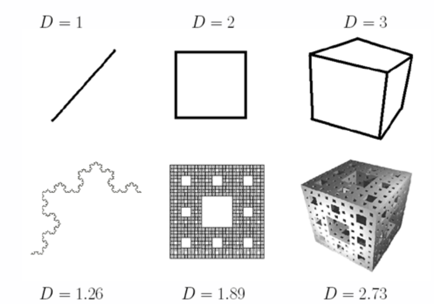
. . . from integer to non-integer . . .



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Interpolation of operations

$$f, \ \frac{df}{dt}, \ \frac{d^2 f}{dt^2}, \ \frac{d^3 f}{dt^3}, \ \ldots$$

$$f, \ \int f(t)dt, \ \int dt \int f(t)dt, \ \int dt \int dt \int f(t)dt, \ \ldots$$

$$\ldots, \ \frac{d^{-2} f}{dt^{-2}}, \ \frac{d^{-1} f}{dt^{-1}}, \ f, \ \frac{df}{dt}, \ \frac{d^2 f}{dt^2}, \ \ldots$$

Slide credit: Igor Podlubny

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"Fractional Order Thinking" or, "In Between Thinking"

- For example
  - Between integers there are non-integers;
  - Between logic 0 and logic 1, there is the fuzzy logic;
  - Between integer order splines, there are "fractional order splines"
  - Between integer high order moments, there are noninteger order moments (e.g. FLOS)
  - Between "integer dimensions", there are fractal dimensions
  - Fractional Fourier transform (FrFT) – in-between time-n-freq.
  - Non-Integer order calculus (fractional order calculus – abuse of terminology.) (FOC)

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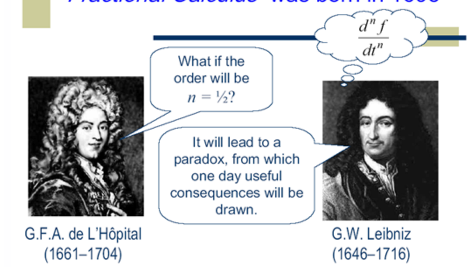
Fractional Calculus was born in 1695



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G. W. Leibniz (1695–1697)

In the letters to J. Wallis and J. Bernulli (in 1697) Leibniz mentioned the possible approach to fractional-order differentiation in that sense, that for non-integer values of n the definition could be the following:

$$\frac{d^n e^{mx}}{dx^n} = m^n e^{mx},$$

L. Euler (1730)

$$\frac{d^n x^m}{dx^n} = m(m-1)\ldots(m-n+1)x^{m-n}$$

$$\Gamma(m+1) = m(m-1)\ldots(m-n+1)\,\Gamma(m-n+1)$$

$$\frac{d^n x^m}{dx^n} = \frac{\Gamma(m+1)}{\Gamma(m-n+1)}x^{m-n}.$$

Euler suggested to use this relationship also for negative or non-integer (rational) values of n. Taking $m=1$ and $n=\frac{1}{2}$, Euler obtained:

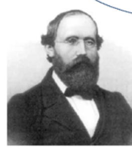
$$\frac{d^{1/2}x}{dx^{1/2}} = \sqrt{\frac{4x}{\pi}} \qquad \left(= \frac{2}{\sqrt{\pi}}x^{1/2}\right)$$

Slide credit: Igor Podlubny

Riemann–Liouville definition

$${}_aD_t^\alpha f(t) = \frac{1}{\Gamma(n-\alpha)}\left(\frac{d}{dt}\right)^n \int_a^t \frac{f(\tau)\,d\tau}{(t-\tau)^{\alpha-n+1}}$$

$$(n-1 \le \alpha < n)$$



G.F.B. Riemann (1826–1866)

J. Liouville (1809–1882)

Slide credit: Igor Podlubny

Grünwald–Letnikov definition

$${}_aD_t^\alpha f(t) = \lim_{h\to 0} h^{-\alpha} \sum_{j=0}^{\left[\frac{t-a}{h}\right]} (-1)^j \binom{\alpha}{j} f(t-jh)$$

$[x]$ – integer part of x

A.K. Grünwald

A.V. Letnikov

Slide credit: Igor Podlubny

Operator ${}_a\mathrm{D}_t^\alpha$

A generalization of differential and integral operators:

$${}_a\mathrm{D}_t^\alpha = \begin{cases} \mathrm{d}^\alpha/\mathrm{d}t^\alpha & \mathbb{R}(\alpha) > 0, \\ 1 & \mathbb{R}(\alpha) = 0, \\ \int_a^t (\mathrm{d}\tau)^{-\alpha} & \mathbb{R}(\alpha) < 0. \end{cases} \quad (7)$$

There are two commonly used definitions for the general fractional order differentiation and integral, i.e., the **Grünwald-Letnikov definition** and the **Riemann-Liouville definition**.

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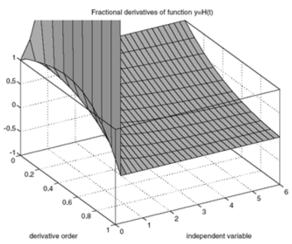
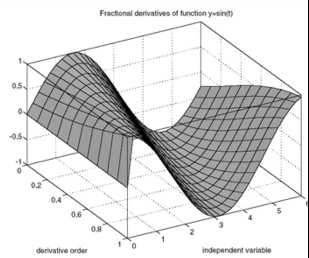
Example: Heaviside's unit step



Example: $\sin(t)$



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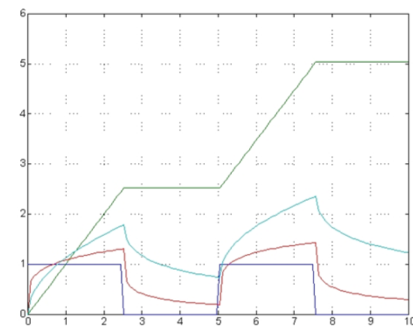
Fractional derivatives of ramp function.



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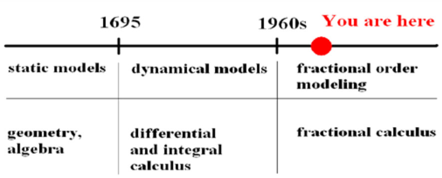
Why and How and When

•Why – Many reasons. Dynamic systems modeling and controls. Better characterization, better control performance
How – Analog versus digital realization methods. Many.
When – **Now**. Ubiquitous. Take a try since we have the new tool. **The beginning of a new stage**



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Modeling: heat transfer

$$\frac{\partial^2 y(x,t)}{\partial x^2} = k^2 \frac{\partial y(x,t)}{\partial t}, \quad (t>0, \quad 0<x<\infty)$$

$$y(0,t) = m(t)$$
$$y(x,0) = 0$$
$$\left|\lim_{x\to\infty} y(x,t)\right| < \infty$$

Transfer function:

$$\frac{\mathrm{d}^2 Y(x,s)}{\mathrm{d}x^2} = k^2 s Y(x,s)$$
$$Q(0,s) = M(s)$$
$$\left|\lim_{x\to\infty} Y(x,s)\right| < \infty$$

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$$Y(x,s) = A(s)e^{-kx\sqrt{s}} + B(s)e^{kx\sqrt{s}}$$

$$A(s) = Y(0,s) = M(s)$$
$$B(s) = 0$$

$$Y(x,s) = M(s)e^{-kx\sqrt{s}}$$

$$G(s) = \frac{Y(x,s)}{M(s)} = e^{-kx\sqrt{s}}$$

think about transfer function $e^{-\sqrt{s}}$!

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FO Controller + IO Plant

Fractional order speed control of DC motor

System transfer function $G(s) = \frac{k}{Js(Ts+1)}$ J being the payload inertia. Phase margin of controlled system:

$$\Phi_m = \arg\left[C(j\omega_g)G(j\omega_g)\right] + \pi$$

Controller: $C(s) = k_1 \frac{k_2 s + 1}{s^\alpha}$, $k_2 = T$ giving a **constant phase margin**:

$$\Phi_m = \arg\left[C(j\omega)G(j\omega)\right] + \pi = \arg\left[\frac{k_1 k}{(j\omega)^{(1+\alpha)}}\right] + \pi$$
$$= \arg\left[(j\omega)^{-(1+\alpha)}\right] + \pi = \pi - (1+\alpha)\frac{\pi}{2}$$

Step response:

$$y(t) = \mathcal{L}^{-1}\left\{\frac{kk_1/J}{s\left(s^{1+\alpha} + kk_1/J\right)}\right\} = \left(\frac{kk_1}{J}\right)t^{1+\alpha}E_{1+\alpha,2+\alpha}\left(-\frac{kk_1}{J}t^{1+\alpha}\right) \quad (63)$$

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Mittag-Leffler function: definition

$$E_{\alpha,\beta}(z) = \sum_{k=0}^{\infty} \frac{z^k}{\Gamma(\alpha k + \beta)}, \quad (\alpha > 0, \quad \beta > 0)$$

$$E_{1,1}(z) = e^z,$$

$$E_{2,1}(z^2) = \cosh(z), \quad E_{2,2}(z^2) = \frac{\sinh(z)}{z}.$$

$$E_{1/2,1}(z) = e^{z^2}\operatorname{erfc}(-z);$$

$$\operatorname{erfc}(z) = \frac{2}{\sqrt{\pi}}\int_z^{\infty} e^{-t^2}dt.$$

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G. M. Mittag-Leffler

Professor Donald E. Knuth, creator of TeX:

"As far as the spacing in mathematics is concerned… I took *Acta Mathematica,* from 1910 approximately; this was a journal in Sweden ... Mittag-Leffler was the editor, and his wife was very rich, and they had the highest budget for making quality mathematics printing. So the typography was especially good in *Acta Mathematica.*"

(Questions and Answers with Prof. Donald E. Knuth, Charles University, Prague, March 1996)

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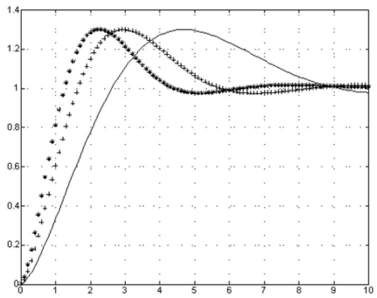

Note the iso-damping (similar overshoot!)

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Fractional operator

- First order differentiator: *s*
- First order integrator: *1/s*

What is s^{α} when α is a *non-integer*?

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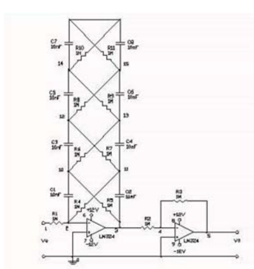
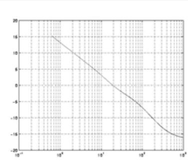
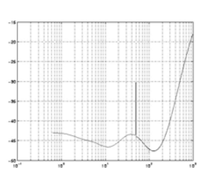
Possible? Possible!



Magnitude plot (dB vs. rad./sec.)



Phase plot (deg. vs. rad./sec.)



Analog $1/\sqrt{s}$ using op-amps.

I. Petras, I. Podlubny, P. O'Leary, L. Dorcak, and Vinagre B. "**Analogue Realization of Fractional Order Controllers**". FBERG, Technical University of Kosice, Kosice, Slovak, **ISBN 8070996277** edition, 2002.

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Fractor: Analogue device

Fractional Calculus Day at USU, April 19, 2005

Photo credit: Igor Podlubny

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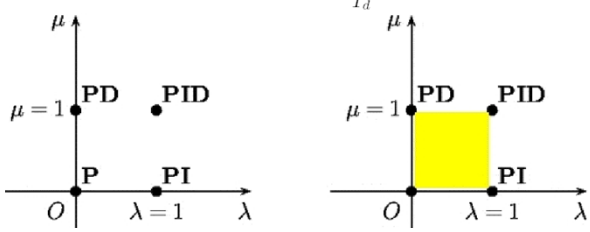
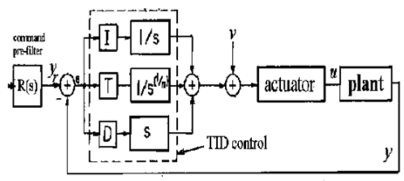
Fractional order PID control

- 90% are PI/PID type in industry. (**Ubiquitous**)

$$u(t) = K_p(e(t) + T_i D_t^{-\lambda} e(t) + \frac{1}{T_d} D_t^{\mu} e(t)). \qquad (D_t^{(*)} \equiv_0 D_t^{(*)}).$$



Igor Podlubny. "*Fractional-order systems and PI^λD^μ-controllers*". IEEE Trans. Automatic Control,44(1): 208–214, 1999.
YangQuan Chen, Dingyu Xue, and Huifang Dou. "**Fractional Calculus and Biomimetic Control**". IEEE Int. Conf. on Robotics and Biomimetics (RoBio04), August 22-25, 2004, Shengyang, China.

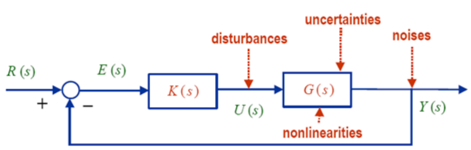


US05371670 on TID by B. J. Lurie, 1994

"3-param. tunable tilt-integral-deriv. controller"

Fractional Order Controls

- **IO Controller + IO Plant**
- **FO Controller + IO Plant**
- **FO Controller + FO Plant**
- **IO Controller + FO Plant**



D. Xue and **Y. Chen***, "**A Comparative Introduction of Four Fractional Order Controllers**". Proc. of The 4th IEEE World Congress on Intelligent Control and Automation (WCICA02), June 10-14, 2002, Shanghai, China. pp. 3228-3235.

Think "fractional order"

- **Fractional-order Systems and Controls -** Fundamentals and Applications
- Series: Advances in Industrial Control
- **Monje**, C.A., **Chen**, Y., **Vinagre**, B.M., **Xue**, D., **Feliu**, V.
- 1st Edition., 2010, XXII, 418 p. 100 illus. With online files/update., Hardcover
- ISBN: 978-1-84996-334-3

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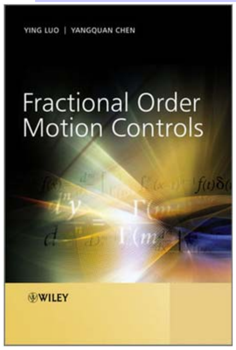
FOMC book by Wiley (Dec. 2012)



Fractional Order Motion Controls
Ying Luo (Original Author), YangQuan Chen (Original Author)
ISBN: 978-1-1199-4455-3
Hardcover
424 pages
December 2012
US $145.00

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Fractional Order Signal Processing

- Additional characterization
- Infinite variance issue (2^{nd} order moment)
- Long range dependence
- Time-frequency approach (FrFT)

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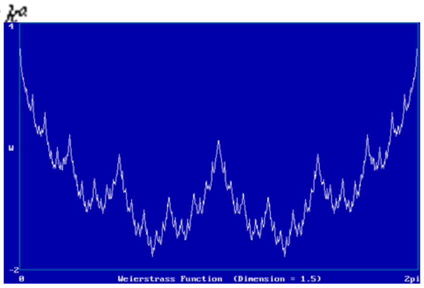
Example-1: Weierstrass function

$$f_a(x) = \sum_{k=1}^{\infty} \frac{\sin(\pi k^a x)}{\pi k^a}$$

- Nowhere differentiable!

Fractional order derivative exists



differentiability order 0.5 or less

sprott.physics.wisc.edu/phys505/lect11.htm

Wen Chen. "Soft matters". Slides presented at 2007 FOC_Day @ USU.

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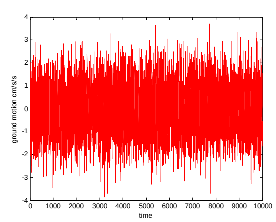
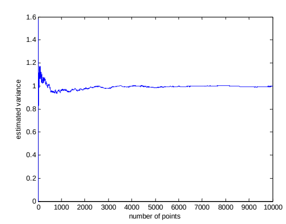
Noise - 1





Normal distribution N(0,1) Sample Variance

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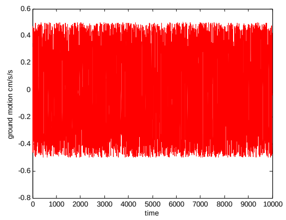
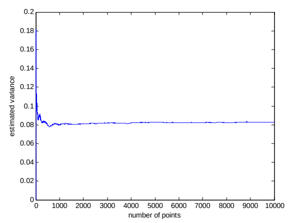
Noise - 2





Uniformly distributed   Sample Variance

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Fractional Lower Order Statistics (FLOS) or Fractional Lower Order Moments (FLOM)

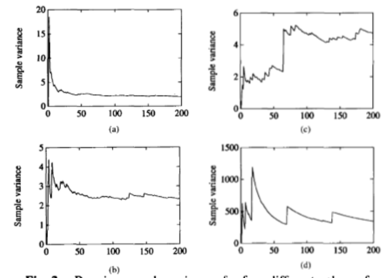

Fig. 2. Running sample variances for four different values of α: (a) $\alpha = 2.0$; (b) $\alpha = 1.9$; (c) $\alpha = 1.5$; (d) $\alpha = 1.1$.

Shao, M., and Nikias, C. L., 1993. "Signal processing with fractional lower order moments: stable processes and their applications". Proceedings of the IEEE, 81 (7) , pp. 986 – 1010.

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Important Remarks

A simple test of infinite variance is to plot the running sample variance estimate S_n with respect to number of points n where $S_n^2 = (\sum_{k=1}^{n}(x_k - \bar{x}_n)^2)/(n-1)$ and $\bar{x}_n = \sum_{k=1}^{n} x_k/n$. For finite variance processes x_k, S_n will converge to a constant value as n increases. If S_n does not converge to a constant value, x_k is a non-Gaussian infinite-variance process with fractional lower order $\alpha < 2$.

In fact, for a non-Gaussian stable distribution with characteristic exponent α, only the moments of orders less than α are finite. Therefore, variance can no longer be used as a measure of dispersion and in turn, many standard signal processing techniques such as spectral analysis and all least squares (LS) based methods may give misleading results.

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Long-range dependence

- History: The first model for long range dependence was introduced by Mandelbrot and Van Ness (1968)
- Seen in: financial data
  communications networks data
  video traffic, biocorrosion data, …
  signals from nature & man-made systems

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Long-range dependence

- Consider a second order stationary time series $Y = \{Y(k)\}$ with zero mean. The time series Y is said to be long-range dependent if

$$r_Y(k) = EY(k)Y(0) \sim c_Y|k|^{-\gamma}, k \to \infty, 0 < \gamma < 1$$

$$s_Y(\xi) \sim c_s|\xi|^{-\alpha}, 0 < \alpha < 1,$$

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GSL: Do you care about it?

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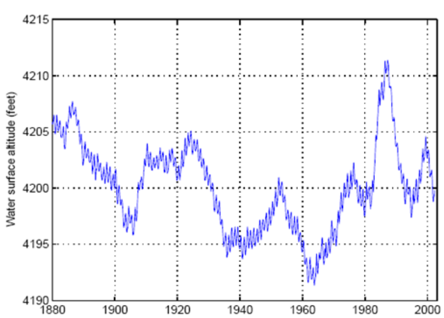
Long-term water-surface elevation graphs of the Great Salt Lake



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Elevation Records of Great Salt Lake

- The Great Salt Lake, located in Utah, U.S.A, is the fourth largest terminal lake in the world with drainage area of 90,000 km^2.
- The United States Geological Survey (USGS) has been collecting water-surface-elevation data from Great Salt Lake since 1875.
- The modern era record-breaking rise of GSL level between 1982 and 1986 resulted in severe economic impact. The lake levels rose to a new historic high level of 4211.85 ft in 1986, 12.2 ft of this increase occurring after 1982.
- The rise in the lake since 1982 had caused 285 million U.S. dollars worth of damage to lakeside.
- According to the research in recent years, traditional time series analysis methods and models were found to be insufficient to describe adequately this dramatic rise and fall of GSL levels.
- This opened up the possibility of investigating whether there is long-range dependence in GSL water-surface-elevation data so that we can apply FOSP to it.

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A recent paper

- Hu Sheng, YangQuan Chen "**FARIMA with stable innovations model of Great Salt Lake elevation time series**" Signal Processing, Volume 91, Issue 3, March 2011, Pages 553-561

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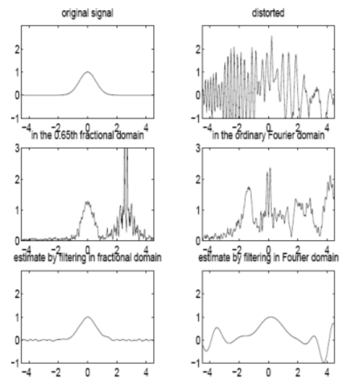
Optimal filtering in fractional order Fourier domain



 Slide credit: HALDUN M. OZAKTAS

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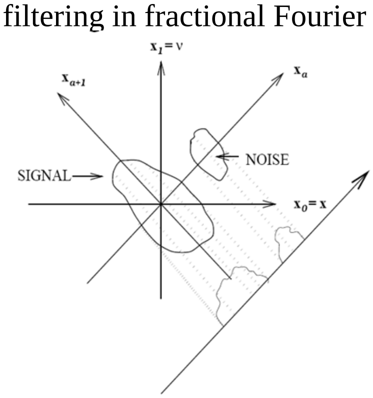
Optimal filtering in fractional Fourier domain



 Slide credit: HALDUN M. OZAKTAS

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A main reference (101 references cited)

- YangQuan Chen* and Rongtao Sun+ and Anhong Zhou. "An Overview of Fractional Order Signal Processing (FOSP) Techniques". DETC2007-34228 in *Proc. of the ASME Design Engineering Technical Conferences*, Sept. 4-7, 2007 Las Vegas, NE, USA, 3rd ASME Symposium on Fractional Derivatives and Their Applications (FDTA'07), part of the 6th ASME International Conference on Multibody Systems, Nonlinear Dynamics, and Control (MSNDC). 18 pages.

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FOSP Techniques

- Fractional derivative and integral
- Fractional linear system
- Autoregressive fractional integral moving average
- 1/f noise
- Hurst parameter estimation
- Fractional Fourier Transform
- Fractional Cosine, Sine and Hartley transform
- Fractals
- Fractional Splines
- Fractional Lower Order Moments (FLOM) and Fractional Lower Order Statistics (FLOS)

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Fractional Calculus, LRD, Power Law,

$u(t)$ → $H(s)=\frac{1}{s^{\alpha}}$ → $y(t)$

White Noise

$h(t)=\frac{t^{\alpha-1}}{\Gamma(\alpha)}$

$Ryy(\tau)=\sigma^2\frac{|\tau|^{2\alpha-1}}{2\Gamma(2\alpha)\cos\alpha\pi}$

y(t) is a Brownian motion when α=1, i.e., $1/f^2$ process.

$1/f^{2\alpha}$ noise (signal) generation via fractional dynamic system

Power laws in

- •Signal/Systems
- •Probability distribution
- •Random processes (correlation functions)

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Rule of thumb for Fractional Order Thinking

- Self-similar
- Scale-free/Scale-invariant
- Power law
- Long range dependence (LRD)
- $1/f^{a}$ noise

- Porous media
- Particulate
- Granular
- Lossy
- Anomaly
- Disorder
- Soil, tissue, electrodes, bio, nano, network, transport, diffusion, soft matters (**bio**x) …

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Power law and power law Lyapunov

- "Power law is ubiquitous" – John Doyle 2001 IEEE CDC Plenary Talk http://www.cds.caltech.edu/~doyle/CDC2001/index.htm
- "When you talk about power law, you are talking actually about fractional order calculus!" – YangQuan Chen 2006 IFAC FDA06 Plenary Talk
- "Lyapunov is ubiquitous in control literature" – ibid.

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Intuitions

- One does not have to be rich to be smart.
- One does not have to be smart to use fractional order calculus.
- **A dynamic system does not have to make the "*generalized energy*" decay exponentially to be stable!**

Y. Li, Y. Q. Chen and I. Podlubny. "Mittag-Leffler Stability of Fractional Order Nonlinear Systems", *Automatica*, 45(8): 965-1969, 2009. DOI: 10.1016/j.automatica.2009.04.003

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Outline

- Fractional Calculus and Fractional Order Thinking
- From Control, Signal Processing to Energy Informatics and Beyond
- Concluding Remarks

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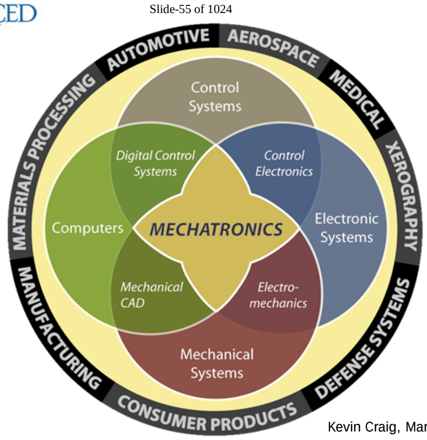

Kevin Craig, Marquette Univ.

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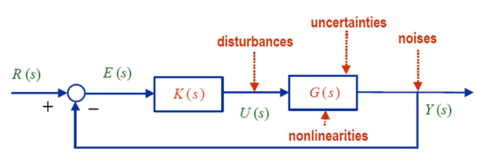
Fractional Order Controls

- `IO Controller + IO Plant`
- `FO Controller + IO Plant`
- `FO Controller + FO Plant`
- `IO Controller + FO Plant`



D. Xue and **Y. Chen***, "**A Comparative Introduction of Four Fractional Order Controllers**". Proc. of The 4th IEEE World Congress on Intelligent Control and Automation (WCICA02), June 10-14, 2002, Shanghai, China. pp. 3228-3235.

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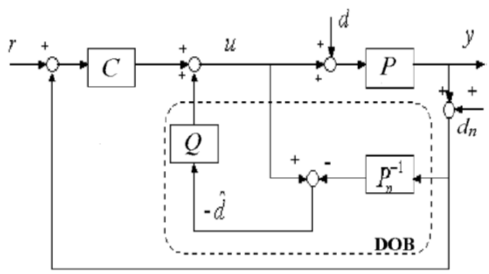
YangQuan Chen*, Blas M. Vinagre and Igor Podlubny. "Fractional order disturbance observer for vibration suppression", (Kluwer) Nonlinear Dynamics , Vol. 38, Nos. 1-4, December 2004, pp. 355-367.



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Attacked topics

- Fractional order adaptive control
- Fractional order PI/D control
- Most recently
  - Fractional order conditional integrator (e.g. Clegg integrator) (JPC)
  - Fractional order consensus seeking (IEEE SMC-B 10)
  - Fractional order optimal control (MATLAB Toolbox)
  - Fractional order model predictive control (of green building?)

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How to design/tune FOC for motion control?

$C(s) = K_p(1 + K_d s^{\mu})$ $\quad P(s) = \frac{1}{s(Ts+1)}$

(i) Phase margin specification

$$\mathrm{Arg}[G(j\omega_c)] = \mathrm{Arg}[C(j\omega_c)P(j\omega_c)] = -\pi + \phi_m,$$

(ii) Robustness to variation in the gain of the plant

$$\left(\frac{\mathrm{d}(\mathrm{Arg}(C(j\omega)P(j\omega)))}{\mathrm{d}\omega}\right)_{\omega=\omega_c} = 0,$$

with the condition that the phase derivative w. r. t. the frequency is zero, i.e., the phase Bode plot is flat, at the gain crossover frequency. It means that the system is more robust to gain changes and the overshoots of the response are almost the same.

(iii) Gain crossover frequency specification

$$|G(j\omega_c)|_{dB} = |C(j\omega_c)P(j\omega_c)|_{dB} = 0.$$

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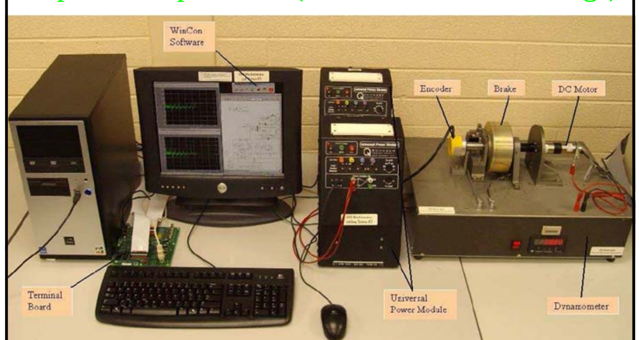
Experiment platform (now in Castle, working!)



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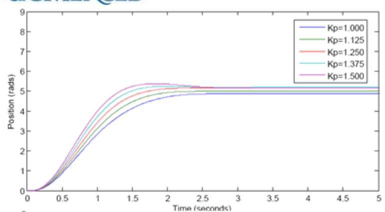
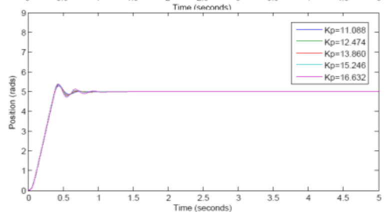


ITAE optimal P controller



FOPD controller.

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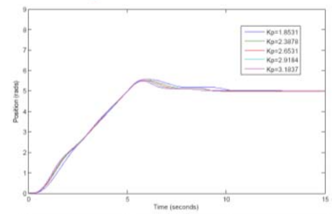
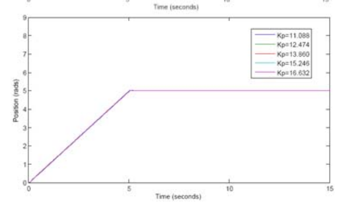


ITAE optimal PI controller



FOPD controller.

IEEE Trans. Control Systems Technology, 2010 18(2):516-520

DOI:10.1109/TCST.2009.2019120

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Impressive Performance!

- How about FO[PD]?

$$C_3(s) = K_{p3}[1 + K_{d3}s]^{\mu}$$

- Note: FOPD shown previously is:

$$C_2(s) = K_{p2}(1 + K_{d2}s^{\lambda})$$

Ying Luo, Y. Q. Chen "Fractional order [proportional derivative] controller for a class of fractional order systems" *Automatica*, 45(10) 2009, pp 2446-2450.

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Smart Mechatronics

Biomimetic Materials and Biomimetic Actuators

- EAP (electroactive polymers), a.k.a. artificial muscle
- ferroelectric and relaxor materials
- piezoceramic and piezopolymetric materials
- liquid crystal elastomers
- electro and magnetostrictive materials
- shape memory alloys/polymers
- intelligent gels etc.

However, little has been reported on the controls of actuators made with these biomimetic materials.

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Compensation of nonlinearity with memory

- e.g., hysteresis, backlash.
- My Assertion: Fractional calculus may better help us.

A Hidden Evidence

IEEE TRANSACTIONS ON CONTROL SYSTEMS TECHNOLOGY, VOL. 9, NO. 1, JANUARY 2001 17

Phase Control Approach to Hysteresis Reduction

Juan Manuel Cruz-Hernández, *Member, IEEE,* and Vincent Hayward, *Member, IEEE,*

***Abstract*—This paper describes a method for the design of compensators able to reduce hysteresis in transducers, as well as two measures to quantify and compare controller performance. Rate independent hysteresis, as represented by the Preisach model of hysteresis, is seen as an input–output phase lag. The compensation is based on controllers derived from the "phaser," a unitary gain operator that shifts a periodic signal by a single phase angle. A "variable phaser" is shown to be able to handle minor hysteresis loops. Practical implementations of these controllers are given and discussed. Experimental results exemplify the use of these techniques.**

***Index Terms*—Compensation, hysteresis, intelligent materials, phase control, piezoelectric transducers, smart materials, transducers.**

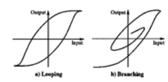

Fig. 1. Hysteresis loop and branching.

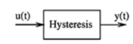

Fig. 2. A black box representation of hysteresis.

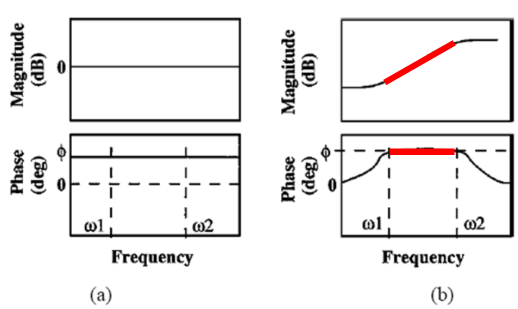

Fig. 10. Frequency response. (a) Ideal phaser. (b) Approximation.

"smart material" based Fractor™

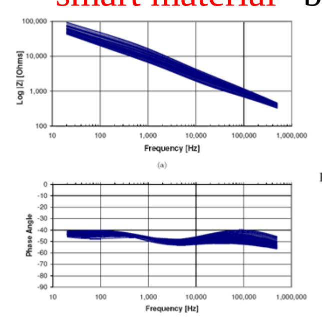

Fig. 1. Spectral response of the Fractor™ used in this demonstration project; (a) the impedance magnitude and (b) impedance phase. The multiple lines show the variation over 26 impedance measurement scans.

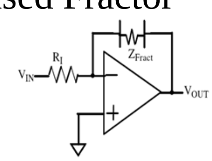

Fig. 2. Schematic for a fractional order integrator. Z_F represents the Fractor™ element. The schematic symbol for the Fractor™ was designed to give the impression of a generalized Warburg impedance; a mixture of resistive and capacitive characteristics.

Gary W. Bohannan "**Analog Fractional Order Controller in a Temperature Control Application**". Proc. of the 2nd IFAC FDA06, July 19-21, 2006, Porto, Portugal.

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Big Picture, or,
The take-home message

- The big picture for the future is the intelligent control of biomimetic system using biomimetic materials with fractional order calculus embedded. In other words, it is definitely worth to have a look of the notion of ``*intelligent control of intelligent materials using intelligent materials*."

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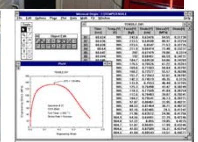
USU Material Research Laboratory

- **Materials Processing, Heat Treating, Materials Joining, and Powder Metallurgy Studies using the Gleeble 1500D System**



Source: http://www.mae.usu.edu/faculty/leijun/gleeble.html

NSF NER: Solid-state synthesis of nano-scale hydrogen storage materials by bulk mechanical alloying http://www.mae.usu.edu/faculty/leijun/

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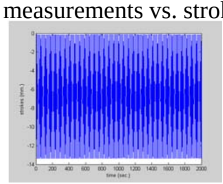
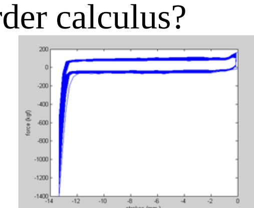
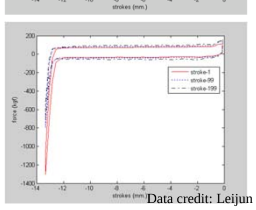
Fractional order calculus?

- Dynamic force measurements vs. strokes







Data credit: Leijun Li

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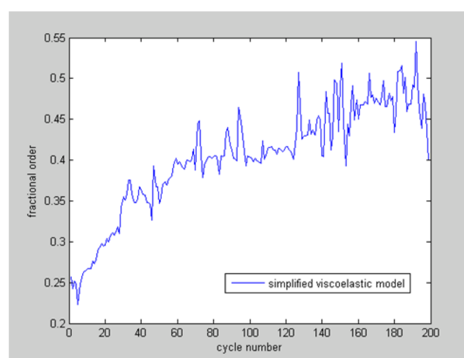
Fractional order vs. strokes



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Big picture of nanoparticle manufacturing

- Now: given cycles, given stroke profile, see how particulate process evolves.
- Future: Production process development – given final particle grain size distribution, how to achieve this by using minimum number of cycles with possible cycle-to-cycle, or run-to-run (per several cycles) adaptive learning control with variable stroke profiles.

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Fractional order ILC (iterative learning control)?

- D-alpha type ILC with a (really good) reason?!
  - YangQuan Chen and Kevin L. Moore. ``*On D^{α}-type Iterative Learning Control*''. Presented at the IEEE Conference on Decision and Control (CDC'01), Dec. 3-7, 2001, Orlando, FL, USA. pp.4451-4456. http://www.csois.usu.edu/publications/pdf/pub054.pdf

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Biomechatronics

Electronically controlled leg and hand prosthesis, neural prosthesis, retinal implants, assistive and rehabilitative robots ...
-- "Emerging Trends and Innovations in Biomechatronics" by Frost & Sullivan

Source: http://www-personal.umich.edu/~ferrisdp/NSF/research.htm

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Biomechatronics

- Biomechatronics is the interdisciplinary study of biology, mechanics, and electronics. Biomechatronics focuses on the interactivity of biological organs (including the brain) with electromechanical devices and systems.
- Universities and research centers worldwide have taken notice of biomechatronics in light of its potential for development of advanced medical devices and life-support systems.

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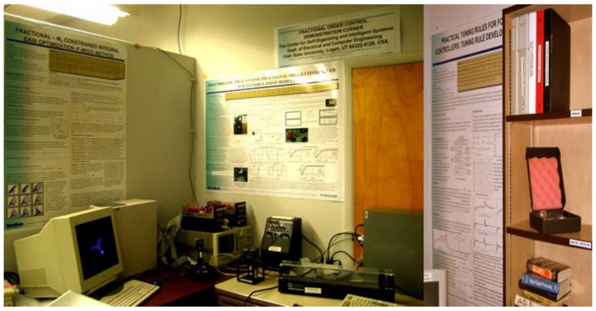
CFOSE - DEMONSTRATION CORNER



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Applications – C-FOSE Proposal (Center for Fractional Order Systems Engineering)

1. Human-augmentation
2. Human Nerve System
3. Robotic equipment
4. Electric drive systems
5. Power Converters
6. Disk drive servo
7. Audio signal processing
8. Aircraft
9. Automobiles
10. Fuel cells
11. Lidar, radar, sonar, ultrasonic imaging
12. Battery chargers
13. Nuclear reactors
14. Temperature Control
15. Biosensor signal processing

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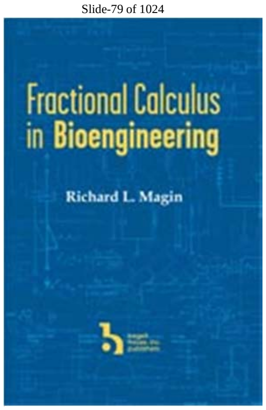

ISBN 1-56700-215-3 ; 978-1-56700-215-7

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Books by Bruce J. West

- 2006. **Where Medicine Went Wrong: Rediscovering the Path to Complexity (Studies of Nonlinear Phenomena in Life Science)**
- 2003. Biodynamics: Why the Wirewalker Doesn't Fall
- 1995. **The Lure of Modern Science: Fractal Thinking (Studies of Nonlinear Phenomena in Life Sciences, Vol 3)**
- 1994. Fractal Physiology
- 1991. Fractal Physiology & Chaos in Medicine (Studies of Nonlinear Phenomena in Life Science, vol. 1)
- 1986. An Essay on the Importance of Being Nonlinear (Lecture Notes in Biomathematics)

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Our recent work

- YangQuan Chen*, Anhong Zhou, Rongtao Sun+ and Nikita Zaveri+. "Fractional Order Signal Processing of Electrochemical Noises". **Journal of Vibration and Control**. Vol. 14, No. 9-10, 1443-1456 (2008) DOI: 10.1177/1077546307087438
- Yan Shi+, Huifang Dou, Anhong Zhou* and YangQuan Chen. "Design and fabrication of a miniaturized electrochemical instrument and its preliminary evaluation" **Sensors & Actuators: B. Chemical**. 131 (2008) 516–524 doi:10.1016/j.snb.2007.12.053
- Anhong Zhou and YangQuan Chen*, **"**Fractional Order Processing of Quartz Crystal Microbalance Based DNA Biosensor Signals**."** *The Second IFAC Symposium on Fractional Derivatives and Applications* (IFAC FDA06) 19 - 21 July, 2006. Porto, Portugal.

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Most recent works

- A fractional order signal processing (FOSP) technique for chemotaxis quantification using video microscopy. 4th ASME/DETC FDTA 09.
- Analysis of electrochemical noise (ECN) of TiO2 nanoparticles coated Ti-6Al-4V in simulated biofluids using fractional order signal processing (FOSP) techniques. 4th ASME/DETC FDTA 09.

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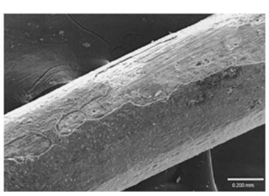
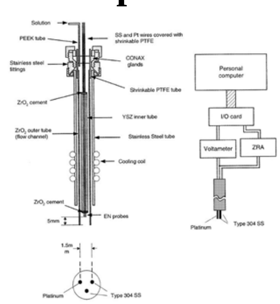
Biocorrosion /Bioimplants





X.Y.Zhou, et al./ *Corros. Sci*. 44(2002) 841-860

Biocompatibility study needs a non-destructive method –
Electrochemical noise (ECN) *measurement offers unique advantages !*

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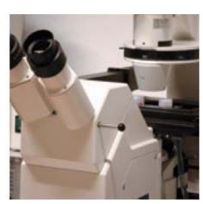
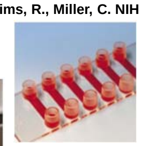
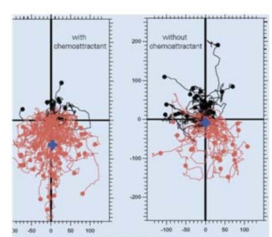
Chemotaxis characterization

Zhou, A. (PI), Chen, Y.Q., Sims, R., Miller, C. NIH R15 Grant# ES013688-01A1 (2006-2009)







Slide credit: A. Zhou

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Image/vision related work

- Dali Chen, Hu Sheng, YangQuan Chen* and Dingyu Xue. "Fractional order variational optical flow model for motion estimation" **Philosophical Transactions of Royal Society A** (to appear)
- Dali Chen, YangQuan Chen* and Dingyu Xue. "1-D and 2-D digital fractional order Savitzky-Golay Differentiator". **Signal, Image and Video Processing,** 2012, Volume 6, Number 3, Pages 503-511
- Dali Chen, YangQuan Chen* and Dingyu Xue. Adaptive Fractional Order Diffusion Model for Robust Image Denoising. **IEEE Trans. IP**, (revised)

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For more FOSP and applications, see

- http://mechatronics.ece.usu.edu/foc/fospbook/
- Hu Sheng, YangQuan Chen and Tianshuang Qiu ***"Fractional Processes and Fractional Order Signal Processing: Techniques &Applications"***
  - Foreword by Professor Richard L. Magin
  - Springer-Verlag, 2012, 318 pages
  - http://www.springer.com/engineering/signals/book/978-1-4471-2232-6

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Now, energy informatics

- Energy Informatics http://cei.usc.edu/
  - "Energy+Information < Energy"
    - energy experts,
    - computer scientists, and
    - social and behavioral studies experts
- Papers/articles (as of 3/3/2011)
  - ISI: 3 ; ScienceDirect: 37; ieeeXplore: 6 ; Google: 3280; GoogleScholar: 193

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"data mining" @ ieeeXplore (x1000)

- Control/820; network/1100; signal/1087; comm*/1182;energy/847; power/1013; system/2117; circuit/1439; education/50;
- Kalman/15; Lyapunov/15; Kharitonov/0.328; Youla/0.337
- Observer/14; feedforward/15; feedback/105; **optim*/325**
- Adaptive/118; nonlinear/149;stability/123; linear/195; robust/83
- Fuzzy/55; neural/94; cybernetics/35; physical/82; chemical/83
- Friction/10; hyster*/19; dead*/13; vision/63; image/297;pattern/177
- PID/7; UAV/2; interval/26; anomal*/12.3; random/82; stochastic/40
- Geometrical/17; algebraic/11; **math*/667; fluctuation/30; noise/202**
- **Forecast/21.4; demand/56.6; behavi*/143; social/18.5**

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Signal -> Information -> Knowledge -> Wisdom

- **Signals** are from man-made large scale, complex systems, usually LRD (long range dependent)
  - Enabled by "cyberinfrastructure", anything, anytime, anywhere
- **Information** is the third essence of the natural world supplementing matter and **energy**
  - Extract from signals considering FOSP!
- **Knowledge is in particular useful in social context (behavior, policy level)**
  - Put information in (social) context
- **Wisdom**: ?

Opportunities

- Battery Management Systems
- Demand/load forecast
  - FOSP for FLOM processes; LRD + infinite variance
- Inference from variability
  - Hypothesis in social contexts
- Social behavior modeling (energy consumption/conservation)
- Culture model (energy consumption)
- Policy implications, optimal trading/pricing etc.

So, what's beyond?

Rule of thumb for Fractional Order Thinking – about everything

- Self-similar
- Scale-free/Scale-invariant
- Power law
- Long range dependence (LRD)
- $1/f^{a}$ noise

- Porous media
- Particulate
- Granular
- Lossy
- Anomaly
- Disorder
- Soil, tissue, electrodes, bio, nano, network, transport, diffusion, soft matters (**bio**x) …

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Outline

- Fractional Calculus and Fractional Order Thinking
- From Control, Signal Processing to Energy Informatics and Beyond
- Concluding Remarks

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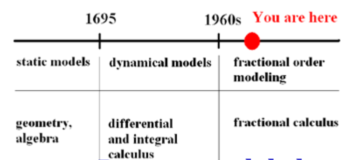
Concluding remarks

- “Go west, young man.” – Horace Greeley
- “Go Fractional.” – YangQuan Chen
- **Fractional Order Thinking enables exciting multidiscipline joint research that matters!**

The beginning of a new stage



Do more and do better!!

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G.W. Scott Blair (1950):

“We may express our concepts in Newtonian terms if we find this convenient but, if we do so, we must realize that we have made a translation into a language which is foreign to the system which we are studying.”

S. Westerlund (1991):

“Expressed differently, we may say that Nature works with fractional time derivatives.”

K. Nishimoto (1989):

“The fractional calculus is the calculus of the XXI century.”

To probe further

http://www.tuke.sk/podlubny/
http://mechatronics.ece.usu.edu/foc/

Slide credit: Igor Podlubny

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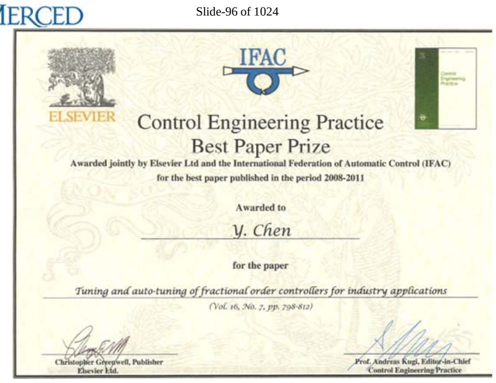

- Fractional Order System – official keyword of IFAC
- pid12.ing.unibs.it/

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Acknowledgements

- Tomi for serving as my role model!
- NRC Twinning Grant, 2003-2005. (Igor Podlubny, K. Moore co-PIs)
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- USU SDL Skunk Works Grant, 2005-2006 (Anhong Zhou, co-PI)
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- Igor Podlubny, Ivo Petras, Lubomir Dorcak, Blas Vinagre, Shunji Manabe, J.T.M. Machado, J. Sabatier, Om Agrawal, Kevin L. Moore, Dingyu Xue, Anhong Zhou, Richard L. Magin, Wen Chen, Changpin Li, Yan Li.
- Concepción A. Monje, José Ignacio Suárez, Chunna Zhao, Jinsong Liang, Hyosung Ahn, Tripti Bhaskaran, Theodore Ndzana, Christophe Tricaud, Rongtao Sun, Nikita Zaveri, …

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Backup slides

- Invited Plenary Lecturer, IPC Member, 3rd IFAC Int. Workshop on Fractional Derivatives and Applications (FDA08), Ankara, Turkey, Nov. 2008.
- IFAC FDA2006 Plenary Speaker
- IFAC FDA2010 Program Chair
- IFAC FDA 2012 (Nanjing, China, Award Chair)

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Q/A Session

- Apologize for not citing carefully math/phyx FOC papers and for not referring to more complete FOC literatures
- Check **http://mechatronics.ece.usu.edu/foc** for more information.
- Jinsong Liang. "**Control of Linear Time-Invariant Distributed Parameter Systems: from Integer Order to Fractional Order**". MS thesis, Electrical and Computer Engineering Dept. of Utah State University, 2005. (119 pages)
- Mr. Rongtao Sun. "**Fractional Order Signal Processing: Techniques and Applications**", ibid, 2007.
- Chunna Zhao. "**Research on Analysis and Design Methods of Fractional Order Systems**". PhD thesis, Northeastern University, China, 2006.
- Concepci´on Alicia Monje Micharet. "**Design Methods of Fractional Order Controllers for Industrial Applications**". PhD thesis, University of Extremadura, Spain, 2006.

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Backup slides

- Youtube channels of CSOIS:
  - **http://www.youtube.com/user/MASnetPlatform**
  - **http://www.youtube.com/user/USUOSAM**
  - **http://www.youtube.com/user/FractionalCalculus**

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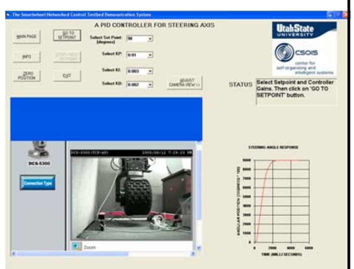
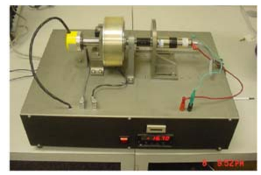
USU Smart Wheel Demo Rig

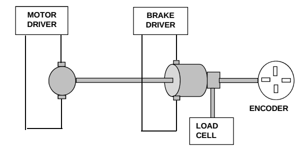
“Omni-directional Robotic Wheel - A Mobile Real-Time Control Systems Laboratory”, Int. J. Eng. Edu. 2008.



http://www.csois.usu.edu/people/smartwheel/CompleteInfoPage.htm

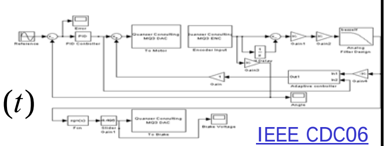
Fractional Horsepower Dynamometer – A General Purpose Hardware-In-The-Loop Real-Time Simulation Platform for Nonlinear Control Research & Education





$$\dot{x}(t) = v(t)$$

$$\dot{v}(t) = -f(t,x) + u(t)$$



IEEE CDC06

Experimental Platform

Quanser Consulting’s SRV02-ET DC motor plants that can be controlled using Simulink interface.

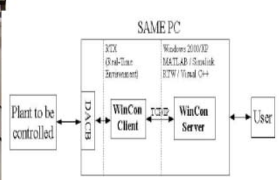


Figure 1. Quanser rotary family mechatronic plants

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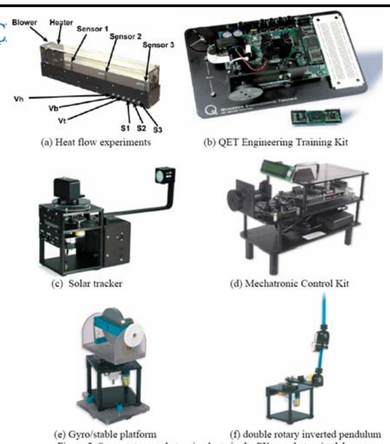

(a) Heat flow experiments (b) QET Engineering Training Kit

(c) Solar tracker (d) Mechatronic Control Kit

(e) Gyro/stable platform (f) double rotary inverted pendulum

Figure 2. Some extra mechatronic plants in the PI's mechatronics lab.

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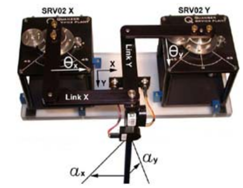

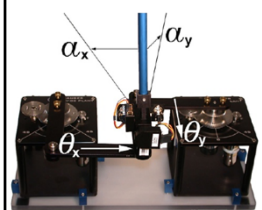

(top left) 2DOF planar Robot

(bottom left) 2DOF inverted pendulum

(top right) 2DOF gantry

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Figure 3. GP-6 analog computer (http://www.comdyna.com/gp6intro.htm)

Fan-n-plate

Many other in-house built mechatronics systems …

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